

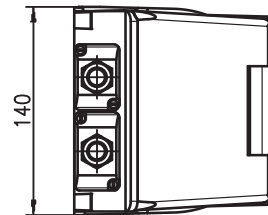
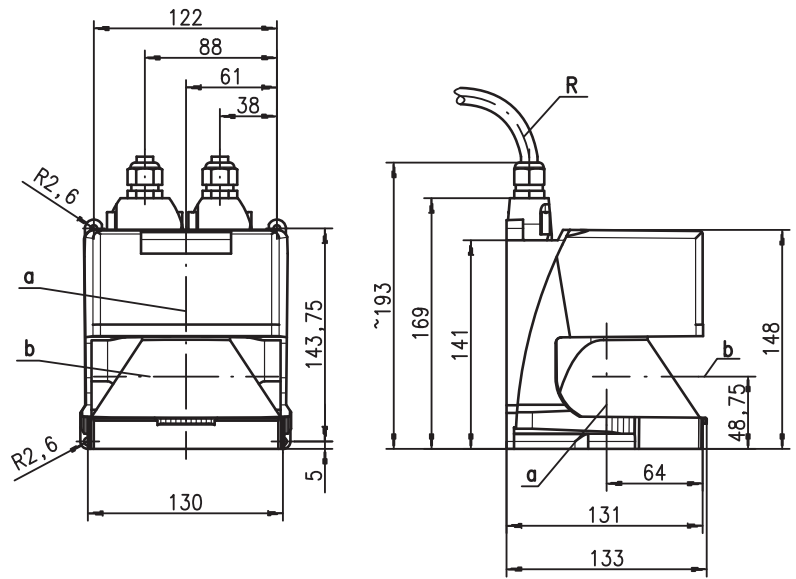
**rotoScan ROD 4-3...**

**Optical Distance Sensors**

Part No. 501 50110694

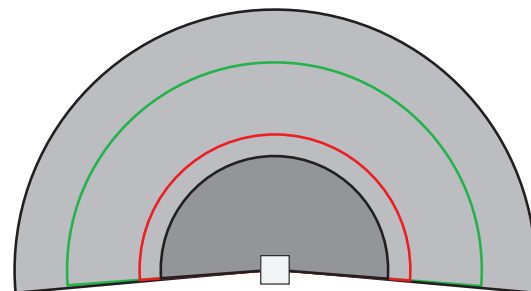
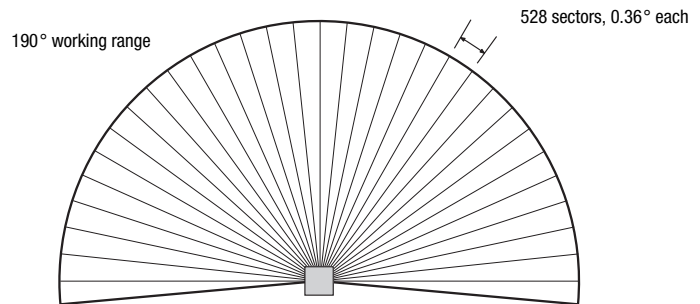


**Dimensioned drawing**

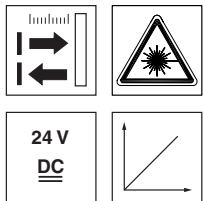


- a** Zero point for measuring
- b** Scanning plane
- R** Smallest bending radius = 50mm

**Measurement principle**



- Meas. range ROD 4-30/ROD 4-36: max. 65m
- Measurement range ROD 4-38: max. 25m
- Radius of far detection field: max. 50m
- Radius of near detection field: max. 30m



**0 ... 65m**

- The rotoScan ROD 4 is an area scanning distance sensor for object detection. The light beam is deflected via a rotating mirror and spread across a semicircular area (190°).
- Max. radius of detection field 50m
- Measurement range 0 ... 65m
- 7 configurable detection field pairs (near and far detection fields) for object detection
- Changeover of detection field pairs via inputs
- Simple device exchange without PC by means of config. connector
- Reference contour for presence/absence checks of objects
- Independent, simultaneous monitoring of 4 detection fields
- Interference suppression in the event of particles in the air
- ROD 4-36 with heating and ROD 4-38 with heating, dust-insensitive version.



**Accessories:**

(available separately)

- Mounting systems
- RODsoft configuration software (free download from [www.leuze.de](http://www.leuze.de))
- Various connection cables

We reserve the right to make changes • DB\_ROD\_4-3x\_gb.fm

## Specifications

### Optical data

Measurement range	0 ... 65 m (ROD 4-38: 0 ... 25m)
Radius of detection field	near: 0 ... 30m far: 0 ... 50m
Angular range	max. 190°
Angular resolution	0.36°
Scanning rate	25 scans/s or 40ms/scan
Transmitter	infrared laser diode, laser class 1 (EN 60815-1), wavelength = 905nm, P <sub>max</sub> = 15W, pulse duration: 3ns, average output power: 12µW

### Detection fields

Reflectivity	from min. 1.8% (matte black), ROD 4-38 from 6% (dark grey)
Object size	> 20mm at distance of 4m, > 100mm at distance of 15m
Response time	at least 40ms (corresponds to 1 scan)
Number of detection field pairs	7 (selectable via switching inputs)
Output	4 x PNP transistor outputs, 24V/250mA
Measur. value resolution	5mm
Repeatability	10 ... 90% diffuse reflection at operating range of 4m: 15mm

### Electrical data

Voltage supply <sup>1)</sup>	+24VDC +20% / -30%
Overcurrent protection	fuse 2A (4A with heating) semi time-lag in the switch cabinet
Current consumption	approx. 400mA (use power supply with 2.5A), approx. 2.5A with heating
Power consumption	< 60W at 24V including the outputs
Overvoltage protection	overvoltage protection with protected limit stop

### Mechanical data

Housing	diecast aluminium, plastic
Weight	2.0kg
Connection type	2 connectors (can be plugged from above, solder connection)

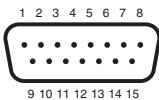
### Environmental data

Ambient temp. (operation/storage)	-0°C ... +50°C / -20°C ... +50°C -20°C ... +50°C / -20°C ... +50°C (ROD 4-36, ROD 4-38)
VDE safety class	III
Protection class	IP 65
Laser class	1 (acc. to EN 60825-1)
Standards applied	IEC 60947-5-2

1) Protective Extra Low Voltage (PELV) - protective extra-low voltage with reliable disconnection.  
For UL applications: only for use in class 2 circuits according to NEC.

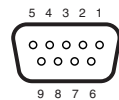
## Electrical connection

X1 - Sub-D - male



GND	1	sw/BK
Restart	2	bl/BU
24 V DC +	3	rt/RD
FPS 1	4	or/OR
Alarm 1	5	ge/YE
FPS 2	6	gn/GN
FPS 3	7	vi/VI
FPS 4	8	gr/GY
NC	9	
NC	10	
Fn1	11	ws/WH
Fn2	12	ws-sw/WH-BK
NC	13	
NC	14	ws-br/WH-BN
Alarm 2	15	br/BN

X2 - Sub-D - female (RS 232/RS 422)



NC	1	
TxD	2	
RxD	3	
NC	4	
GND/SHIELD	5	
RS select	6	NC
NC	7	
NC	8	
reserv.	9	

TxD +	1	
TxD -	2	
RxD -	3	
RxD +	4	
GND/SHIELD	5	
RS select	6	
NC	7	
NC	8	
reserv.	9	

## Order guide

	Designation	Part No.
	ROD 4-30	501 10238
With heating	ROD 4-36	501 10666
With heating/dust-insensitive	ROD 4-38	501 10667

## Tables

### Notices

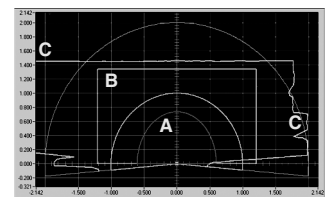
#### "RODsoft" Configuration Software

The configuration software runs under Windows 95/98/NT/2000/XP and offers the following features:

- Definition of the detection fields
- Configuration of the scanner parameters
- Visualisation of the detection fields and measurement values
- Display of status/diagnostic information
- Support of various languages

There are a variety of options available for defining detection fields. These include e.g.:

- "Teach-In" function
- Numeric and graphical input of the detection fields
- "Edit" function



A Near detection field  
B Far detection field  
C Current measurement values

- **Approved purpose:**  
The ROD 4 distance sensors are optoelectronic sensors for the optical, contactless measurement of distance to objects.